EPO-4 code structure:

The program is controlled by the main.py file. This instantiates a possible GUI and, when requested, an instance of the Robot.py class

The Robot.py class includes all data about the robot, like

* Location
* Velocity
* Motor power
* Direction
* State

The robot also includes a list of all subsystems

1. Control
2. Communication
3. Distance
4. Localization
5. Pathing
6. Kalman